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Artificial Intelligence for Road Safety

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Presentation Outline

1. Introduction
2. Big Data Perspectives
3. Surrogate Safety Measures (SSMs)
4. AI Advances in Road Safety Risk Estimation
5. AI + Big Data = Road Safety
6. AI in Telematics, Driver Monitoring & AVs
7. Distraction & Spatial Approaches
8. Pending Barriers
9. Conclusions



Introduction (1/2)

- Road transport is responsible for the majority of transport fatalities, with **1,19 million fatalities** worldwide each year.
- **Road safety** is a field with typically high risk of important investments but not matching results.
- Absence of **monitoring and accountability** limits seriously road safety performance.
- Very often used to look where the **data** are and not where the problems and solutions are.



Introduction (2/2)

- Innovative **data-driven solutions** could contribute to a proactive approach of addressing urban road safety problems, being a core principle of the Safe System Approach.
- The rise of **smartphones, sensors** and **connected objects** offers deeper and broader transport data.
- The interpretation of these data can be made possible thanks to progress in **computing power, data science** and **artificial intelligence**.



The importance of monitoring

- Total number of fatalities allows for **initial comparisons** between countries
- Road safety performance may **differ considerably** with exposure or per crash type
- Disaggregate data can reveal **hidden problems or patterns**
- Authorities can resolve them with **more focused interventions**

Available: <https://www.nrso.ntua.gr/nrso-ec2/>

Fatalities per million population: All EU countries



Date: July 2024, Sources: CARE, Processing: NTUA

2022 data for all EU countries except for Ireland, Latvia (2020) and Malta (2021)



Big Data, Broad Horizons (1/2)

- A wealth of **big data** becomes available.
- Differentiations per road user category and focus on **niche analyses** (e.g. VRUs, professional drivers, freight vehicles etc.).
- A multitude of **data sources**:
 - **Mobile Phone** data:
 - Sensor Based Data (e.g. Google Maps, Here, Waze)
 - Cellular Network Data (e.g. mobile phone operators, etc.)
 - Vehicular **On-Board Diagnostics** data (e.g. OEM industry)
 - **Camera** data:
 - On-vehicle (internal, dash-cam and peripheral)
 - On the road (cities, operators, police)
 - Data from **Car Sharing** Services (e.g. Uber, Lyft, BlaBlaCar)
 - Data from **Micromobility** Operators (e.g. Bolt, Lime, Voi, Tier, Dott)



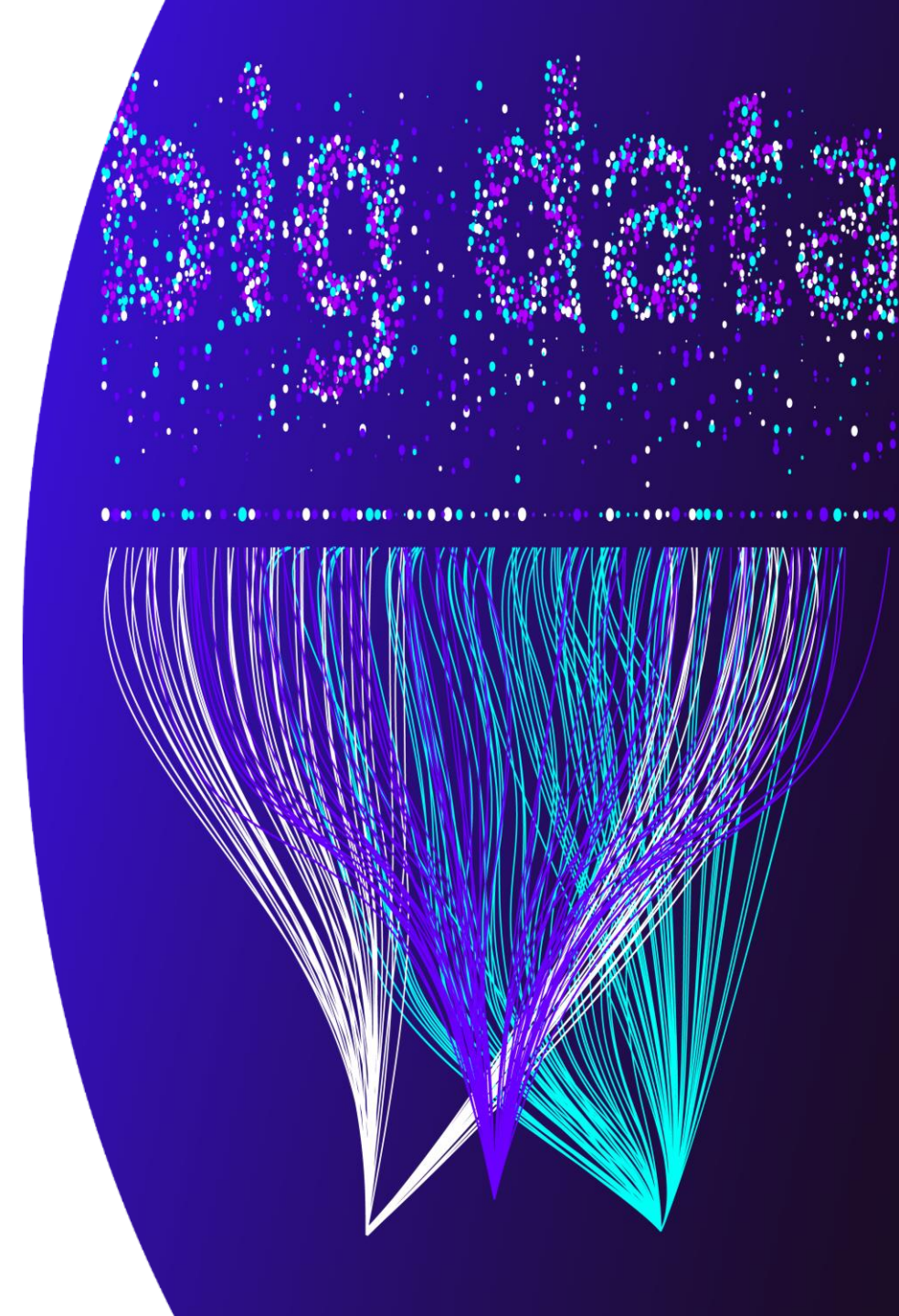
Big Data, Broad Horizons (2/2)

- **Telematics** companies (e.g. OSeven, ZenDrive, Octo, Flow)
- **Private agency sensor** data (e.g. INRIX, Waycare)
- **Travel Card** data (e.g. Public transport)
- **Public authority** sensor or **traffic measurement** data (e.g. Ministries, Public Transport Authorities, Cities, Regions)
- **Weather** data (e.g. OpenWeatherMap, AccuWeather, etc.)
- **Census** data (e.g. Eurostat, National Statistics)
- **Digital map** data (e.g. OpenStreetMap, Google Maps, etc.)
- **Shared mobility** data (e.g. GPS, routing, etc.)
- **Social Media** data (e.g. Facebook, Twitter/X)
- **Research oriented** data (e.g. instrumented vehicles)



Big Data, Big Issues

- The consequences of using data which are **not always representative** of the whole population (bias towards some user groups) should be assessed and properly corrected.
- It is easy to **wrongly consider** a dataset as unbiased if it covers a specific dimension in detail (e.g. covering different road users) while it can fail in another (e.g. not covering exposure).
- **Desired conclusions** should not drive the research approach or outcomes.
- There is a high risk for decision makers to be **misled** by the opportunistic analysis of seemingly low-cost data in absence of **qualified data scientists and statisticians**.



How Open are Big Data?

- Fragmentation of data ownership and a **lack of interoperability** between datasets and platforms.
- Different interests of the various road safety **stakeholders** in data, creating differing requirements for data access.
- **Data ownership** varies by who generates and collects the data and they may be not willing to share data due to privacy, legal liability, IP, competition, or cost related issues.
- Road safety data are often **ethically or commercially** sensitive.
- The diversity of data sources affecting **data quality**.
- **Systems capacity** process big data on traffic and behaviour (real-time, etc.).
- **Lack of expertise** in machine learning, data mining, and data management with a **road safety context**.



Surrogate Safety Measures (SSMs)

- Big Data → **SSMs**, e.g. traffic conflicts, harsh driving events, spatial/temporal headways, and many others.
- Readily available for **proactive analyses** before crashes occur or in areas with limited or no crash data availability.
- SSMs show **less underreporting**; can even aid with crash reporting.
- Research on the **validation** of surrogate safety metrics is essential...
 1. to reveal which metrics not only are correlated with reported crashes but also have predictive capabilities
 2. to forecast the number of fatalities and/or injuries
 3. to determine how these metrics can integrate crash participant fragility, speed, mass and crash type consequences
- More than before, data must **not be misused/misinterpreted**.



AI in Driver Monitoring

- In-cabin AI can prevent **fatigue** and **distraction** by monitoring eye movement, gaze patterns, head or hand position, and reaction times (personalized by driver).
- AI can predict personalized **proactive safety measures** by analyzing historical driver data aiming at predicting potential safety risks (e.g., aggressive driving or stress).
- AI can be employed in AVs to continuously monitor the **driver attentiveness** in real-time especially during Take Over Requests (TORs).
- AI can personalize the AV experience by adapting the **Human-Machine Interface** (HMI) based on the driver preferences and patterns.



AI in Automated Driving

- **Depth perception** (e.g., LiDAR, radar, etc.)
- **Data fusion** from environment data (from cameras, lidar, radar, etc.)
- **Object recognition** and **movement prediction**.
- Dynamic **Decision-Making algorithms** (real-time trajectory planning, optimization and response).
- Vehicle-to-Everything (**V2X**) communication between a vehicle and any entity that may affect, or may be affected by, the vehicle (data exchange).
- Machine Learning for **personalized adaptation** in-cabin and driving experience.



AI Advances in Road Safety Risk Estimation

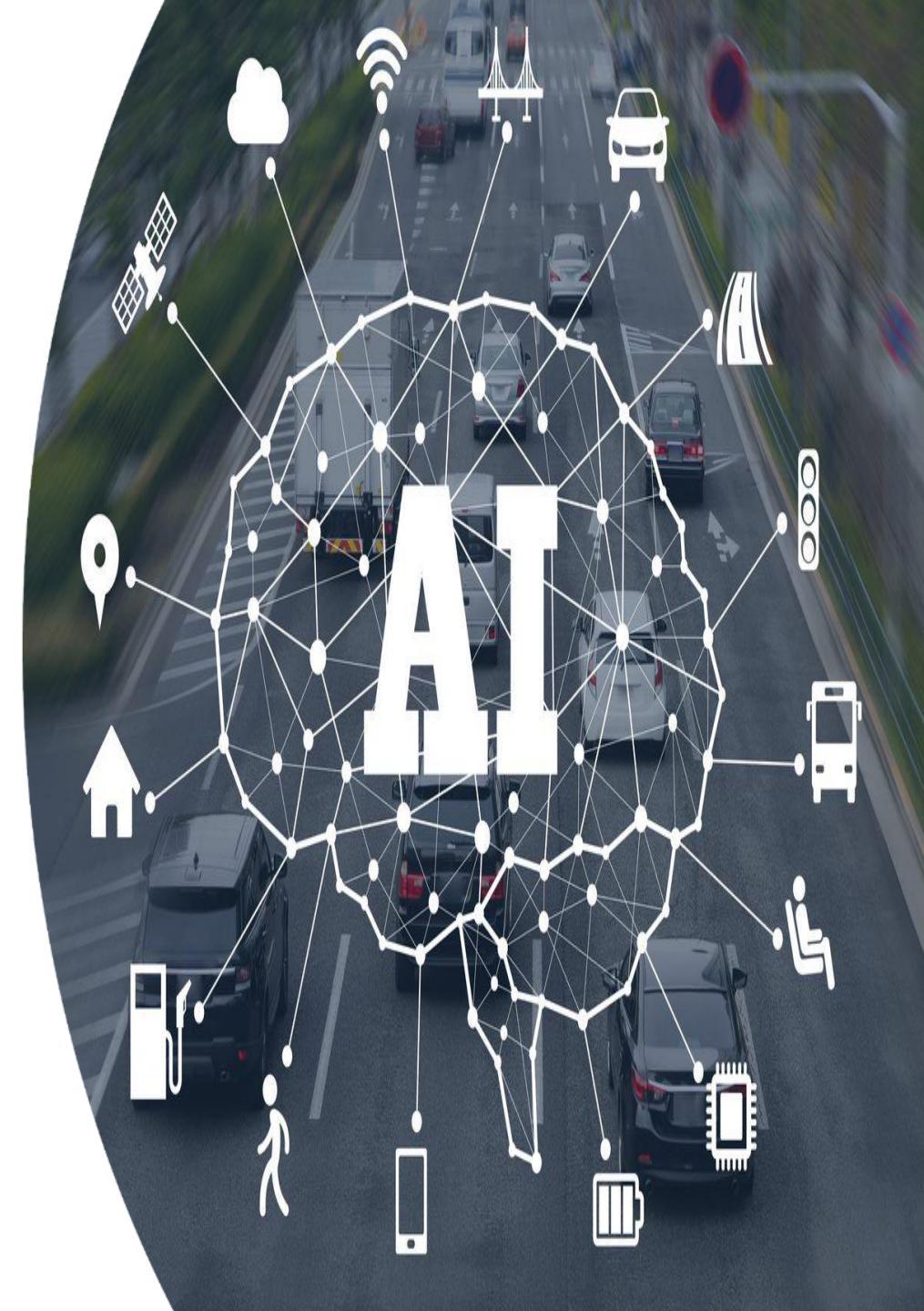
- Methods related to **Artificial Neural Networks** are the most promising for road safety, contributing to ADAS.
- Apart from incident detection, all other problems addressed are **mode-specific**.
- Knowledge could be transferred from the safety field of AVs to **other modes**.
- Pattern recognition has received heightened attention (e.g. **85% accuracy of pedestrian detection** from video recording using Convolutional Neural Networks)
- However, it remains a challenge to detect and block **intentional malicious manipulation** of training datasets.



AI + Big Data = Road Safety

AI facilitates the **proactive management** of traffic safety in various ways:

- Collection of data on road infrastructure conditions and traffic events through wide and broad-scale **sensors and systems** such as real-time computer vision.
- Identification of **high risk locations** proactively, through predictive multi-layer models.
- Enabled by multiparametric big data, AI pushes the limits of **pattern recognition** and **reaction times** beyond human capabilities and may thus uncover new crash-prone road configurations.
- Recent developments in the field of so-called “**explainable AI** (XAI)” begin to cope with the challenge of the “black box” phenomenon.



AI in Telematics & Driver Monitoring

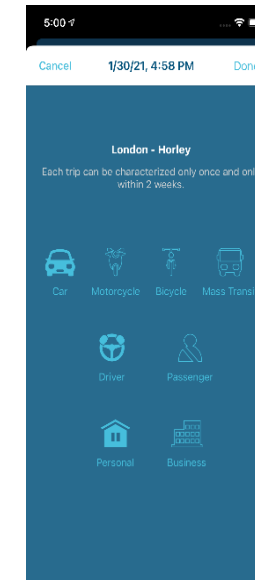
- The **insurance industry** is heavily investing in telematics-based algorithms, offering reduced premiums for safer driving.
- **AI and data fusion** technologies used in all stages of road safety data collection, transmission, storage, harmonization, analysis and pattern detection.
- **Personalized feedback** can be obtained almost instantaneously.



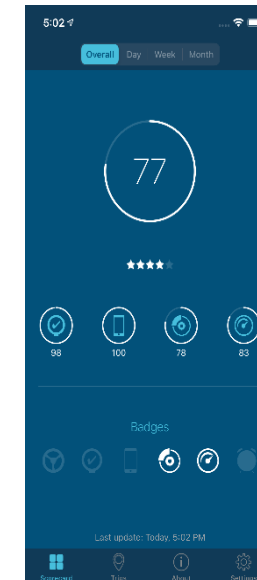
Distraction investigation (1/2)

- An investigation of factors influencing **distraction** from mobile phone use in naturalistic driving.
- A **smartphone application** developed by [OSeven telematics](#) with 6 feedback phases was the basis for data collection for 87 frequent car drivers.
- Utilizes motion **sensors** (e.g. accelerometer and gyroscope), position sensors (e.g. magnetometer), global navigation satellite system (GNSS) receivers etc.
- A number of metrics are recorded that can be used as **SSMs**.

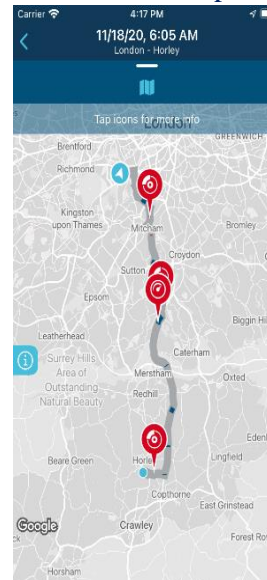
Phase 1 – No feedback



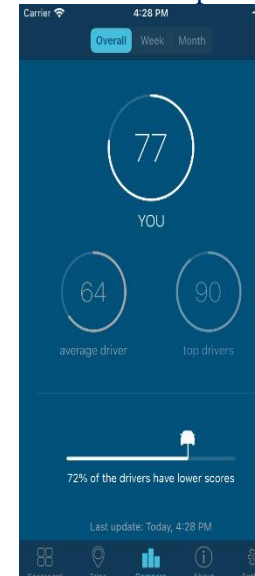
Phase 2 – Scorecard



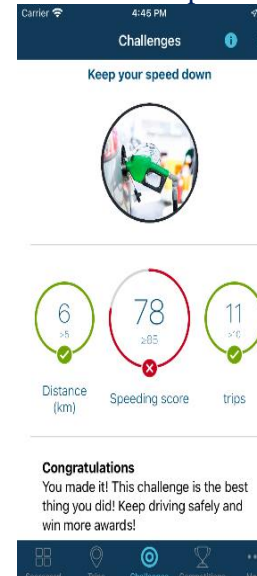
Phase 3 – Maps



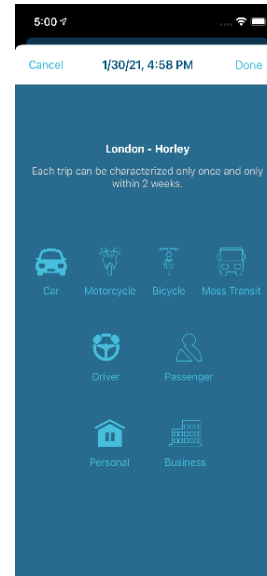
Phase 4 – Comparison



Phase 5 – Competitions



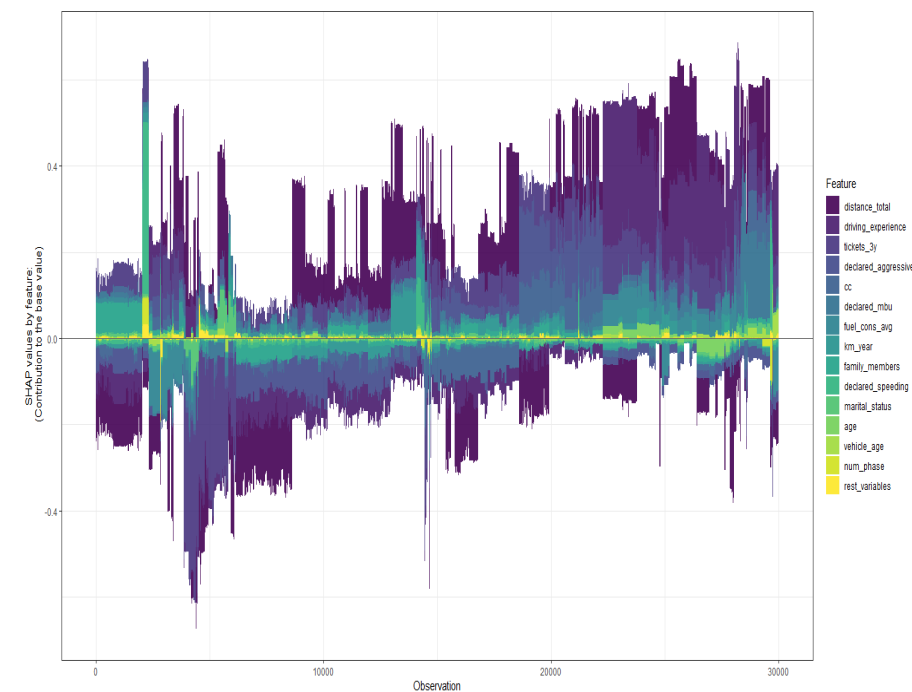
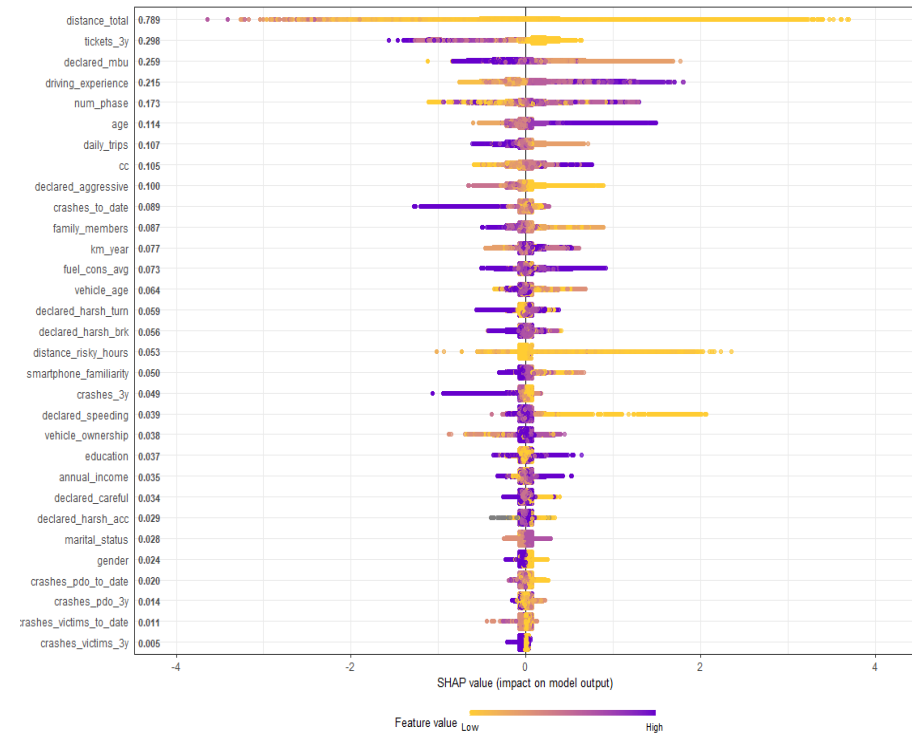
Phase 6 – No feedback



Distraction investigation (2/2)

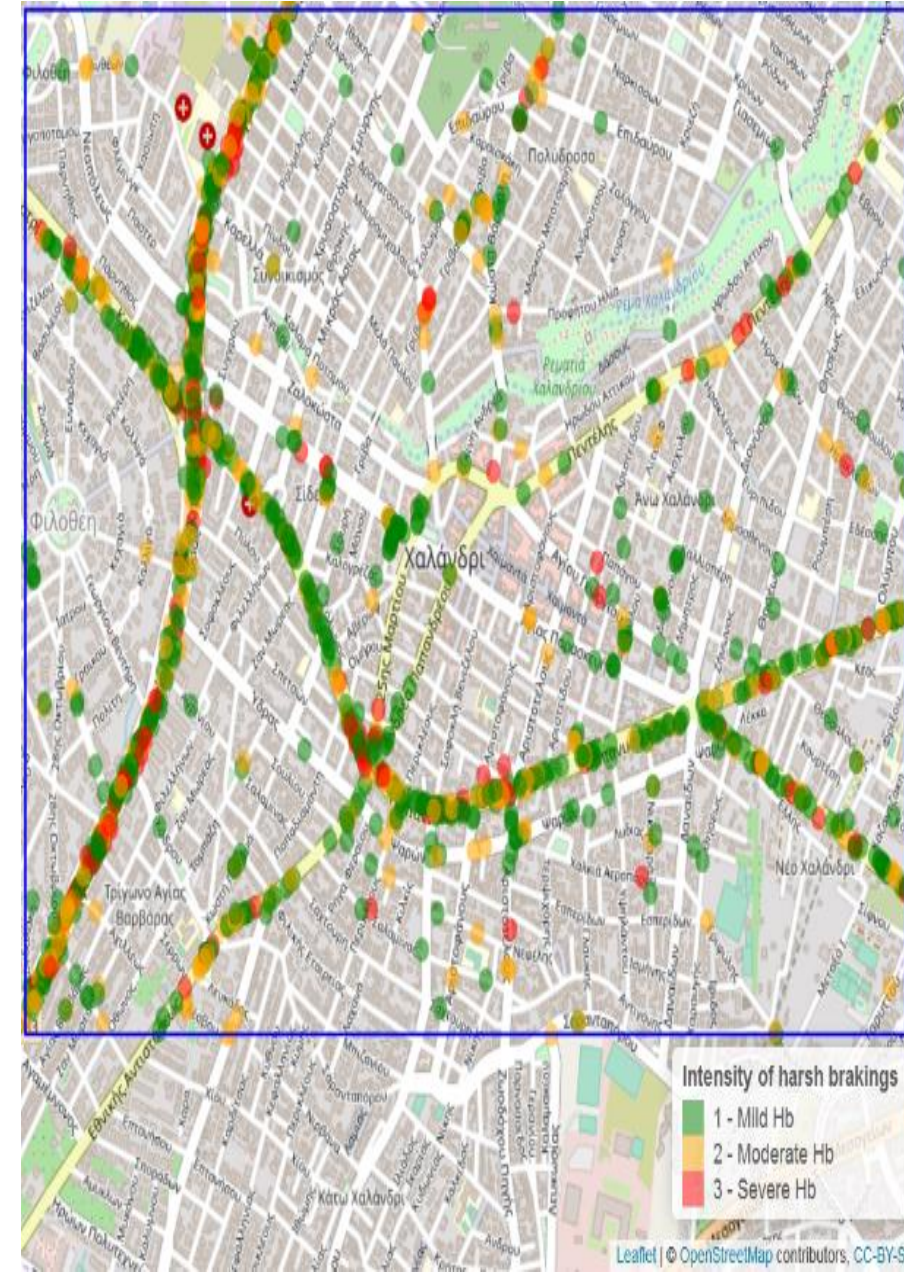
- Explainable XGBoost tree ensemble **ML algorithms** with SHAP values were trained.
- Higher total trip distance, number of tickets & feedback **decrease mobile phone use.**
- Higher driver age & experience, annual kilometers & engine capacity **increase mobile phone use.**

...all in a proactive analysis!



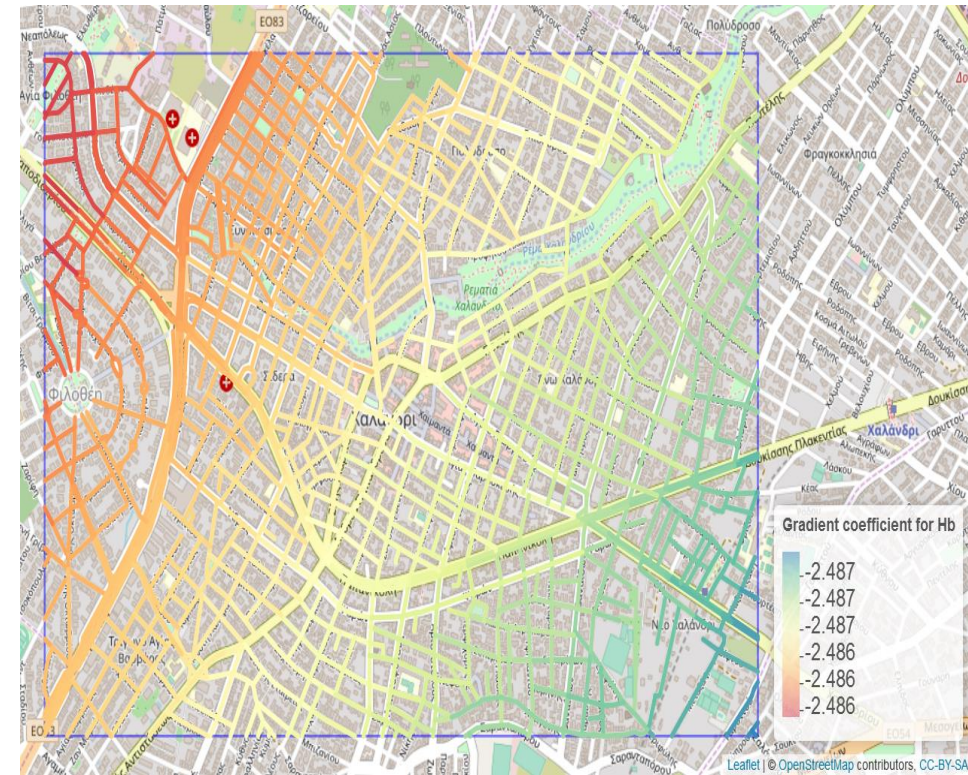
Network Spatial investigation (1/3)

- Smartphone **driving behavior** data & OpenStreetMap **geometric data** are exploited and map-matched.
- **Harsh braking** counts are spatially analyzed in an urban road network.
- 869 road segments (removal of 14 footways) with 4.293 nodes (of which, 49 road with traffic lights, 80 with pedestrian crossings)
- 3.294 trips from 230 drivers, 1.000.273 driving seconds (average trip duration 304s) during 2 months
- 1.348 **harsh brakings** (& 921 **harsh accelerations...**)



Network Spatial investigation (2/3)

- Statistical models GWPR, CAR, and **machine learning** XGBoost models (randomly and spatially cross-validated) were trained.
- After adjustments, counts are predicted in another network to assess **transferability**.
- 87.6% **accuracy** of harsh braking frequencies was achieved, in a fully proactive analysis.
- Indicative **correlations**:
Segment length and pass counts are positively correlated with HBs.
Gradient and neighborhood complexity are negatively correlated with HBs.



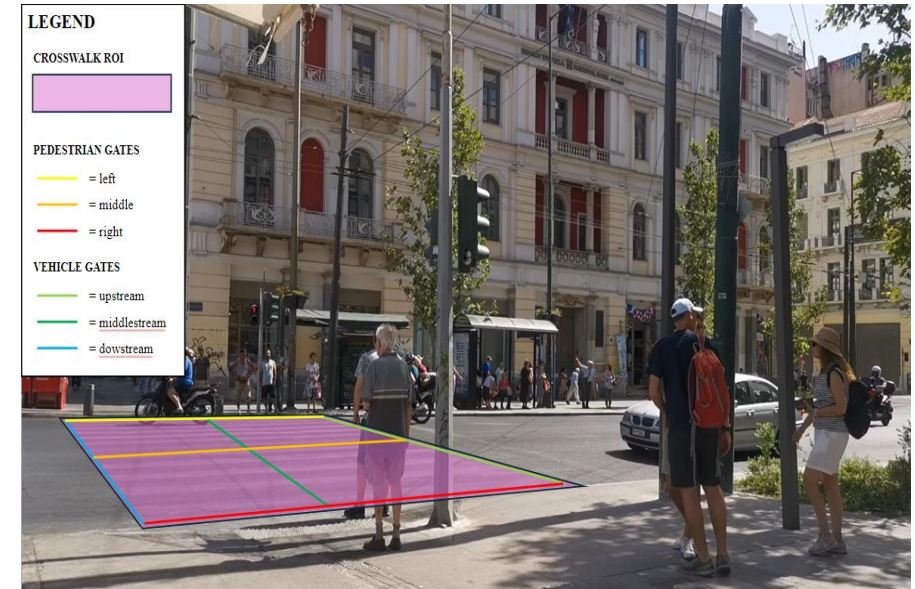
Network Spatial investigation (3/3)

Model weaknesses are covered and strengths are enhanced with **combined predictions**.



Pedestrian behavior from video recognition

- Pedestrians are analysed with a **multi-step** tracking logic:
 1. Object detection,
 2. Consistency tracking,
 3. Matching of detected and tracked objects
 4. Tracking of movement behind occlusions
- **Traffic light status** is determined
- **Illegal crossings** are inferred based on time and traffic light color
- **Time-to-Collision** with oncoming traffic is calculated
- **Higher accuracy of speed monitoring** by authorities can be achieved.



Pending Barriers for AI

- Safe, road-worthy AI systems face significant **challenges** that are only hesitantly tackled:
 - **Interfaceability**
 - **Interoperability**
 - **Timelessness**
 - **Scalability**
- Absence of **monitoring and accountability** limits seriously road safety performance.
- To counter this, increase acceptance and public trust by **monitoring and reporting**.
- Research and innovation efforts on the use of AI in **computer vision** and **risk prediction** needs more support.



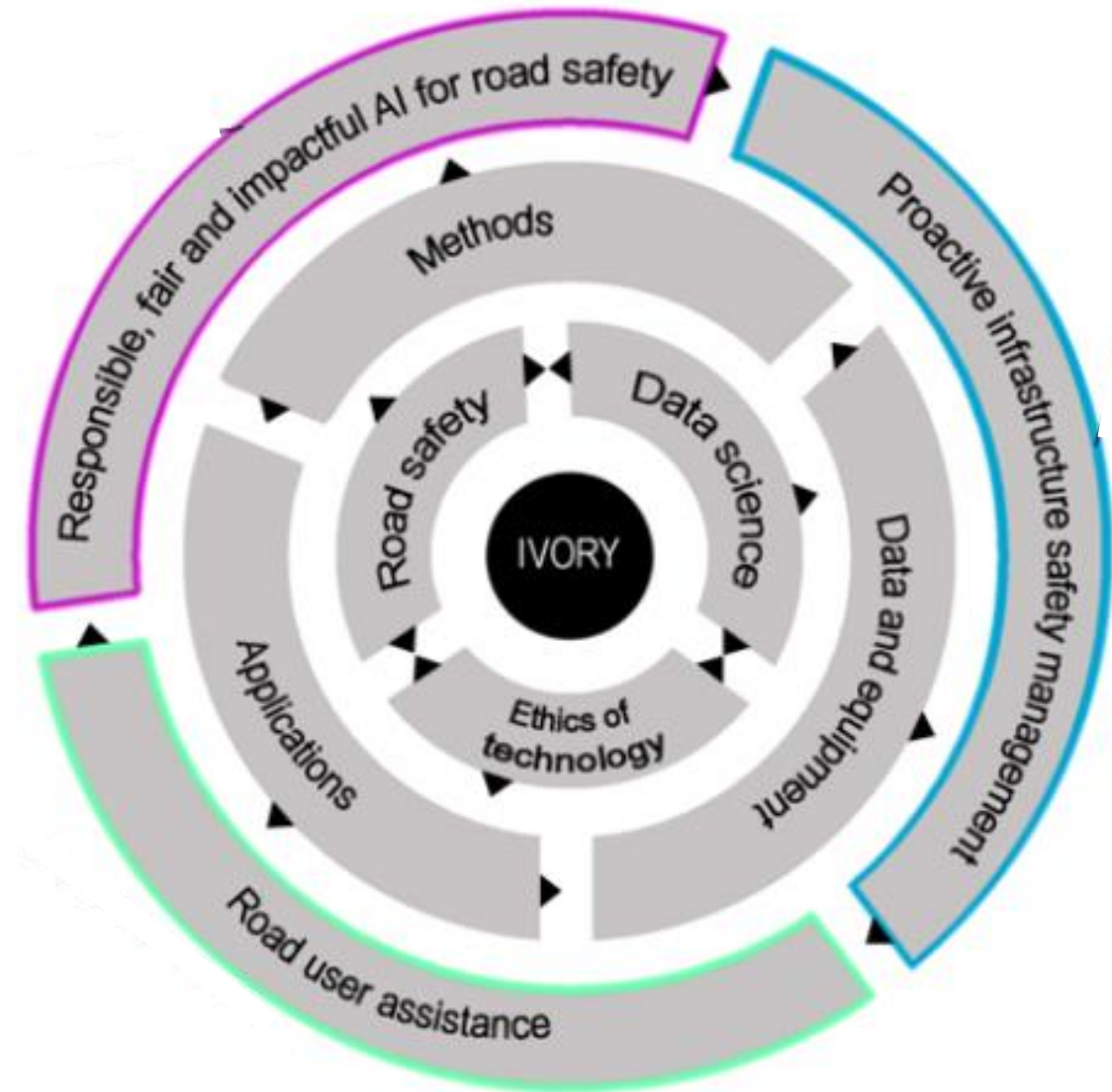
The IVORY MSCA Doctoral Network

Further research: **IVORY – ‘AI for Vision Zero in Road Safety’**

- An EC-MSCA Industrial Doctorates Network, aiming to develop a **new framework for the integration of AI** in road safety and create a new generation of leading researchers

Objectives to be developed:

- **Responsible, fair and impactful** AI for road safety
- **New ways of supporting road users** and human-vehicle-environment interaction by means of AI
- **New scalable and equitable AI technologies** for proactive infrastructure safety management
- **A sustainable learning, knowledge sharing and networking framework** on AI for road safety



Conclusions (1/2)

- Multiple-criteria based exploration and decision analysis to determine the most efficient **Surrogate Safety Measures** that can be mined or obtained from the available Big Data.
- **AI** modelling can reveal complex, non-linear relationships such as factors affecting drivers using a mobile – and be distracted.
- Combining high resolution multi-parametric naturalistic driving, geometric and traffic data to conduct meaningful **spatial analyses** at segment and network level can be proved highly useful.



Conclusions (2/2)

- Road safety practitioners can rapidly gain by copying best practices for **data sharing** and privacy protection from other fields.
- Completely **unexplored directions** remain in several road safety aspects (crowdsourcing options, measure effectiveness, data harmonization).
- Big Data and Artificial Intelligence can become **efficient catalysts** for achieving Vision Zero road fatalities by 2050.



Key Recommendations

- **Integrate lessons learned** from telematics AI for the advent of Connected, Cooperative & Automated Mobility (CCAM)
- **Balance carefully** between accurate road user recording and protesting of the public due to privacy disruptions and AI-based control
- **Foster dialogue** between data holders and policymakers for standardization and more openness of data
- **Invest into training** specialized road safety-oriented computer science professionals





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