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Exploring the Relationship Between Unsafe Traffic Events and Crash Occurrences Using Smartphone App Data

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Significance of Study

- Road crashes are a significant public health issue, with over 1.35 million annual fatalities worldwide
- Current road safety measures show slow progress, necessitating new approaches for crash prediction and prevention.
- Unsafe traffic events, such as harsh accelerations and braking, occur more frequently and are easily obtainable using smartphone app data.
- Leveraging real-time data from smartphone sensors offers a proactive approach to traffic safety analysis and intervention.





State-of-the-art





Driving Behaviour Analysis

Human factors contribute to ~95% of crashes. Analysing behaviours like harsh braking and acceleration is crucial (Singh, 2015).

Sensor Data for Traffic Safety

Smartphone-based data (accelerometers, GPS) has revolutionised behaviours monitoring and safety modelling (Mantouka et al., 2018).

Use of Harsh Event Data

Point-data analysis of harsh events predicts high-risk zones ('hotspots') proactively, improving safety measures (Tselentis et al., 2017).

Research Objectives

- To assess the correlation between unsafe traffic events (e.g., harsh acceleration, braking) and crash occurrences.
- To analyse spatiotemporal patterns of these events using smartphone app data to investigate driver behaviours and safety perception.
- To develop and evaluate regression models to enhance crash prediction accuracy at two of the most used avenues and their intersections in Athens:
 - (i) Mesogeion Avenue
 - (ii) Vouliagmeni Avenue





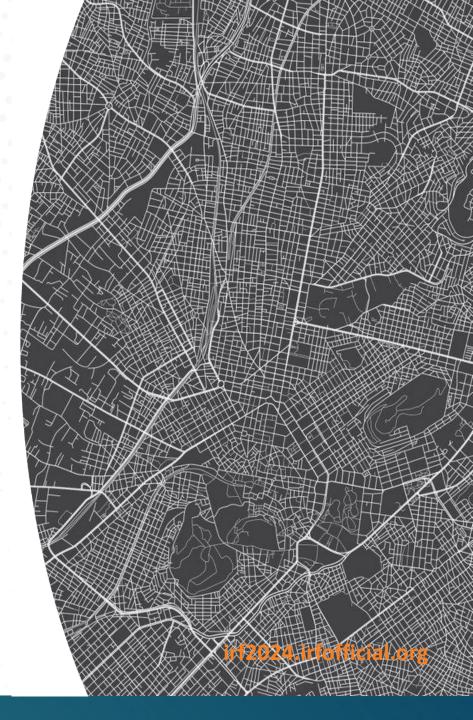
Methodology: Data Sources

• Driving Behavior Data: Collected from ~300 drivers in Athens using the OSeven smartphone app, recording instances of harsh acceleration and braking.

• Traffic Metrics: Obtained from the Attica Traffic Management Center, including traffic volume, average speeds, and occupancy rates.

• Road Characteristics: Extracted from Google Maps, detailing lane configurations and intersection characteristics.



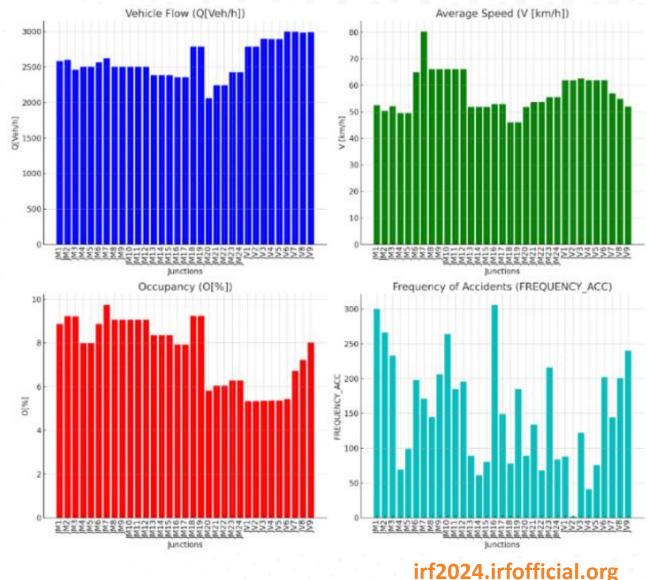


Descriptive Statistics & Patterns

• **Traffic event data** categorised by junctions (avenues of Mesogeion-JM and Vouliagmeni-JV).

 Analysis of variables such as vehicle flow (max J6 – Vouliagmeni), average speed (and max J7 – Mesogeion), occupancy rate (J7-Mesogeion), and frequency of accidents at intersections.

• Identification of high-risk junctions for targeted intervention





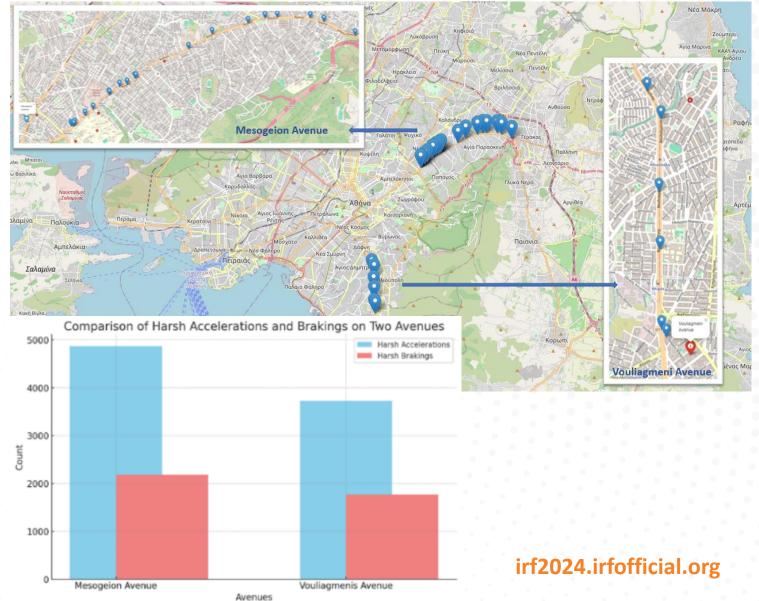
Data Integration & Analysis

• Spatial Mapping: GIS tools were used to correlate unsafe events with specific road segments and intersections.

• Data Standardization: Ensured consistency in data units and formats.

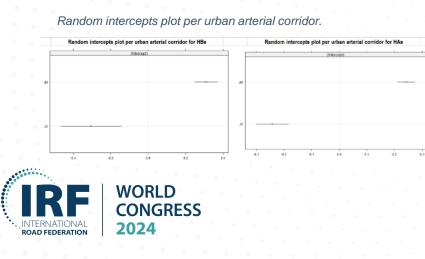
• Event Detection: Harsh events are identified via machine learning algorithms using smartphone sensor data (accelerometer, GPS).





Modeling Approach

- 1. Generalized Linear Models (GLM): Assessed predictor like speed difference, junction characteristics, and traffic metrics.
- Generalized Linear Mixed Models (GLMM): Included 2. random effects for road junction types to capture variability in crash frequency.
- Model Diagnostics: AIC values, deviance, and VIF 3. scores for model selection and validation.



Exploring the relationship between ur	safe traffic events and c	ras	sh occu	rrence using har	sh	acceleratio	n events
	LRT results:						
	Likelihood ratio te	est					
Model 1: FREQUENCY_ACC ~ MIN_S Ri	peed_Diff + MAX_Speed_ ght_Exits + Outgoing_Lan				+ S	TD_Event_	Speed +
Model 2: FREQUENCY_ACC ~ MIN_S Right_Exits	peed_Diff + MAX_Speed_ + Outgoing_Lanes + Side	_			+ S	TD_Event_	Speed +
#Df LogLik	[Df	Chisq	Pr(>Chisq)			
1 8	-340.1						
2 9	-318.01	1	44.185	0.0000000003	***		
Signif. codes: 0 ***	*' 0.001 '**' 0.01 '*' 0.05 '.	' 0.	.1 ' ' 1				
	LRT = significant, so GLM	IEF	R is bette	er			
Exploring the relationship between	unsafe traffic events and	l ci	rash oco	currence using h	ars	h braking	events
and the second	Likelihood ratio te	est					
Model 1: FREQUENCY_BRK ~ MIN_S Ri	peed_Diff + MAX_Speed_ ght_Exits + Outgoing_Lan				⊦ S'	TD_Event_	Speed +
Model 2: FREQUENCY_BRK ~ MIN_Sp Right_Exits	eed_Diff + MAX_Speed_[+ Outgoing_Lanes + Side				Ş	STD_Event	_Speed
#Df LogLik	[Df	Chisq	Pr(>Chisq)			
1 8	-138.31						
2 9	-135.82	4	4,9793	0.02565	+		

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	Base G	LM model	results	Random intercepts GLMER model:							
Coefficients:					1	Fixed effects:					
	Estimate	Std.Error	z value	Pr(> z)			Estimate	Std. Error	z value	Pr(> z)	
(Intercept)	3.901915	0.135481	28.8	< 2e-16	***	(Intercept)	3.609952	0.224784	16.06	< 2e-16	,
MIN_Speed_Diff	-0.10434	0.011044	-9.448	< 2e-16	***	MIN_Speed_Diff	-0.082331	0.011598	-7.099	1.26E-12	*
MAX_Speed_Diff	0.0821	0.005783	14.196	< 2e-16	***	MAX_Speed_Diff	0.076991	0.00591	13.027	< 2e-16	,
MAX_Event_Speed	0.018499	0.001451	12.752	< 2e-16	***	MAX_Event_Speed	0.015155	0.001523	9.954	< 2e-16	*
STD_Event_Speed	-0.128158	0.008623	-14.863	< 2e-16	***	STD_Event_Speed	-0.108751	0.009211	-11.807	< 2e-16	,
Right_Exits	0.299347	0.026149	11.448	< 2e-16		Right_Exits	0.198172	0.030031	6.599	4.14E-11	,
Outgoing_Lanes	-0.126292	0.016905	-7.471	0.00000000000008	***	Outgoing_Lanes	0.003163	0.024918	0.127	0.898988	
Sideway	0.046146	0.03461	1.333	0.1820		Sideway	0.119132	0.035797	3.328	0.000875	1
			<u> </u>			0.01 '*' 0.05 '.' 0.1 ' '		h hasting			
		Y_BRK ~ I	MIN_Spee	ed_Diff + MAX_Spee	ed_D	nd crash occurrence Diff + MAX_Event_Sp y = poisson, data = Vo	eed + STD_I			t_Exits +	
	Base G	LM model	results		-	Rar	ndom interce	pts GLMER	model:		
Coefficients:						Fixed effects:					
	Estimate	Std.Error	z value	Pr(> z)			Estimate	Std. Error	z value	Pr(> z)	
(Intercept)	37.638361	5.876399	6.405	0.000000001504	***	(Intercept)	32.554388	6.144945	5.298	1.17E-07	*1
MIN_Speed_Diff	-0.095534	0.015099	-6.327	0.000000002498	***	MIN_Speed_Diff	-0.05591	0.020027	-2.792		
MAX Canad Diff	0.004004	0 445000	C 445	0.000000001400	***	MAX Canad Diff	0 400457	0 470407	E 47	0.000 07	*1

13.446 < 2e-16

-10.043 <2e-16

0.0000212902784

4.251

-2 42

1.076654

MAX Event Spee

STD Event Speed

Outgoing_Lanes

Right Exits

Sideway

0.026445

-0.103621

0.263377

-0.101075

0.493532

1.17383

0.010318

0.061958

0 04165

074886

Generalized linear models results

Exploring the relationship between unsafe traffic events and crash occurrence using harsh acceleration events Sneed Diff + MAX Sneed Diff + MAX Event Sneed +

			Sigi	III. COC	ies: 0 .00	0.01	0.05 . 0.					
					VIF s	cores	results					
Ex	ploring the r	elatior	nship betwee	en uns	afe traffic ever	its and cra	sh occurr	ence using l	harsh acceleratio	n events		
•	VIF scores for the Base GLM model:											
MIN	_Speed_Diff	MAX	_Speed_Diff	MAX	_Event_Speed	STD_Eve	nt_Speed	Right_Exits	Outgoing_Lanes	Sideway		
	2.036474	0	1.853465		1.772092		1.77632	1.768705	3.948076	1.465606		
	VIF scores for the Random intercepts GLMER model:											
MIN	_Speed_Diff	MAX	_Speed_Diff	MAX	_Event_Speed	STD_Eve	nt_Speed	Right_Exits	Outgoing_Lanes	Sideway		
	1.903179		1.860567		1.868247		1.843664	2.180624	3.54389	1.219679		
	Exploring the relationship between unsafe traffic events and crash occurrence using harsh braking events											
					/IF scores for th	e Base GLI	M model:					
MIN	_Speed_Diff	MAX	_Speed_Diff	MAX	_Event_Speed	STD_Eve	nt_Speed	Right_Exits	Outgoing_Lanes	Sideway		
	2.162926		1.106514		1.813739		1.725633	2.031507	2.88136	1.404447		
			VI	score	es for the Rando	om intercep	ots GLMER	model:				
MIN	Sneed Diff	ΜΑΧ	Sneed Diff	MAX	Event Sneed	STD Eve	nt Sneed	Right Exits	Outgoing Lanes	Sideway		

1.991475

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2 036128

2.006422

0.024633

-0.042743

-0.089453 0.01127

0.225168 0.06359

0 568168 0 07843

STD Event Speed

Outgoing Lanes

Right Exit

0 '***' 0 001 '**' 0 01 '*' 0 05

.00207

0.04665

1.855

-7.936

3 541

0 91

7.243

2.10E-1

00039

35961

4.37E-1

1 96741

Results: Predictive Models & Insights

- Key Predictors: Speed differences, right exits, and side lanes significantly affect crash frequencies.
- **Model Performance:** GLMM outperformed GLM by considering random effects across junction types, providing a better understanding of crash occurrence patterns.
- VIF values (<5) indicate that the predictors are reasonably independent and do not distort the model's results
- Implications: Speed variability and junction design features are critical for safety improvements.
 Mesogeion is more prone to crashes compared to those of Vouliagmeni Avenue.





Limitations & Future Work

Limitations of Current Study:

- Small sample size of junctions may affect generalizability.
- Excluded factors like weather, demographics, and vehicle types can enhance applicability across different contexts.

Future Research Directions:

- Expand data collection to include broader sources, such as weather conditions and vehicle types.
- Conduct detailed behavior analysis to uncover additional risk factors.
- Incorporate machine learning models for improved risk prediction.





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